1782-JDM
DeviceNet™-Modbus Gateway
User's Manual

Western Reserve Controls, Inc.

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1 Overview

The 1782-JDM is a family of DeviceNet-to-Modbus interfaces that allows you to easily connect and integrate a Modbus-capable device into a DeviceNet system.

The Modbus device's real-time data is read and written as I/O by the DeviceNet Master via Polled I/O. The devices set up parameters, if any, can be read and written with the Explicit Messaging technique. The 1782-JDM will operate with any compliant DeviceNet master software system or other device.

The JDM is defined as a Communications Adapter device on the DeviceNet system. It has a 3-pin plug connector to cable to the Modbus RS232 or RS485 interface port on the MODBUS DEVICE and a 5-pin pluggable DeviceNet connector for connections to the DeviceNet network. The DeviceNet baud rate selection is done automatically by the device when it is powered up on a network. The JDM has one assigned DeviceNet address which is set by a 6-position DIP switch on the unit. Other parameters are software-configurable and are changed from their default values by third-party DeviceNet configuration tools. Each JDM has 2 standard green/red DeviceNet LED's for module status and network status and two green LED's to indicate RS485 transmit and receive activity.

All the Modbus device parameters are accessible for read or write over DeviceNet via the JDM, which allows the user the option of using DeviceNet tools and software to define or monitor these parameters in addition to other off-the-shelf or custom software utility using the Modbus port connection.

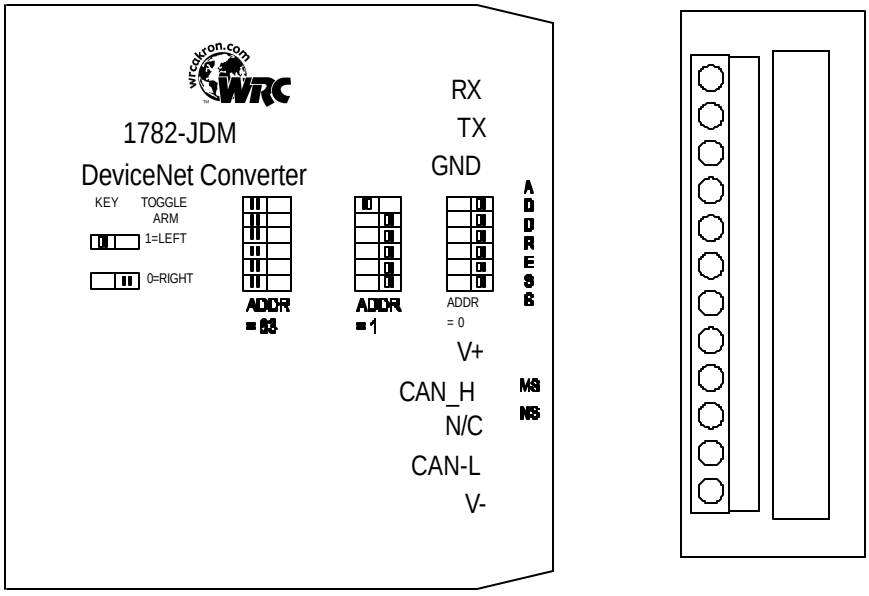

Figure 1-1 1782-JDM

1.1 Features

The JDM has the following features:

- Translates messages and data between DeviceNet and Modbus devices
- Operates independently of operation of Modbus device
- Forwards the message received without interpretation
- Each JDM communicates with one or more Modbus devices
- ODVA Conformance tested to DeviceNet Spec 2.0
- DeviceNet Autobaud operation
- Polled I/O
- Explicit Messaging
- All Modbus registers on target device are accessible
- Upgrades to the Modbus device do not require updates to the JDM
- Software Configurable Parameters for device operation
- Address selection via DIP switches
- DIN rail mount
- Pluggable 5-pin DeviceNet connection
- Pluggable RS232/RS485 3-pin connection
- Choice of RS232, RS485 or isolated RS232 serial interface
- Standard DeviceNet module and network status LED's
- Serial port transmit and receive LED's
- Powered from DeviceNet network
- Optional isolated RS485 interface

1.2 DeviceNet System Architecture

A DeviceNet network is a distributed I/O system that may contain many different products from several different vendors. Products may be configured uniformly, as clusters or as distributed clusters. Up to 64 devices, including the master, may be attached to a single DeviceNet network. Any of these, except the master, may be a JDM. A typical system will include a master, such as a PLC or industrial PC, and multiple slave devices, including a JDM with connected Modbus devices.

1.3 JDM Basic Operation

The JDM operates as the DeviceNet front-end gateway between the DeviceNet system and the Modbus devices. It is a DeviceNet server device that can be assigned by the system implementer to one specific master. The DeviceNet Master can receive and send data to and from the JDM via the methods described in this section. It interprets messages received from the DeviceNet connection, and if its a Modbus message, reformats and sends it to the Modbus device. Likewise, it accepts and interprets responses from the Modbus device, which are reformatted and passed back to the DeviceNet system as required.

The JDM has one DeviceNet address. All Explicit DeviceNet messages to the JDM itself (to read / write its internal data) are sent to this address. The Modbus devices are communicated to using poll messages sent to the JDM and poll responses received from the JDM. See Section 2.4 and 2.5 for details.

The JDM Parameter Object allows you to define the specific operation of each JDM. These parameters include set-up for the serial comm link and the fault and idle actions and data. See Section 3.6 for details.

Each Modbus device connected to the JDM has a Modbus address between 1 and 247. This address is used by the host system and the JDM to identify which device on the Modbus network is being selected for each message.

Table 1-1 Data Message Options

I/O Type	Polled	Cyclic	Bit-Strobe	Change-of-State	Explicit Message
Modbus Device Commands	Õ				
Modbus Device Status	Õ				
JDM Parameters					Õ

The following sections describe how the data is accessed.

1.3.1 Polled I/O

The master can poll the run-time data used in the JDM. The communications is a two-part transaction: there is a Poll Command from the host to the JDM and the JDM responds with a Poll Response using the response of the addressed Modbus device.

How do I send a poll command to write data?

The poll command can set multiple registers of data per output command, depending upon the Modbus command used. First, define the Modbus command string desired to send to the Modbus device. Enter this data in binary format – the normal format for RTU mode. This format is also used if in Modbus ASCII mode – the JDM will translate from binary to ASCII. Do not include the leading colon (for ASCII mode) or the CRC or LRC. Determine the number of bytes to be written, with the data in binary format. Then set up your scanner to write the defined number bytes of data to the JDM **plus one (1)**.

Any Modbus command and register that is appropriate to the target Modbus device are valid. See the Modbus device's user's manual for more details on which commands are supported.

How do I send a poll command to read data?

The poll command can read multiple Modbus Device status registers' data per poll command, as supported by the device, up to a limit of 100 bytes of data on the DeviceNet message. First, set up your scanner to read the number of bytes of data expected from the JDM **plus two (2)**, depending upon the command and number of register data desired. The command response from the Modbus device is returned from the JDM to the DeviceNet master in response to a poll command.

1.3.2 Explicit Messages

As mentioned explicit messages are typically used to read and write configuration data. See the DeviceNet Specification for further information of the standard data available.

1.4 Default Device Configuration

The JDM DeviceNet address is read from the switches and is set to 63 at the factory. All other parameters are software settable. The default settings for the JDM are provided in Section 3.6.

1.5 EDS

An EDS (Electronic Data Sheet), which describes the various parameters of the JDM, is shipped with your device or is available on WRC's web site: http://www.wrcakron.com/

2 Quick Start

To quickly and easily install your JDM in your DeviceNet system, follow the instructions below. For more details, see Section 2.3.

To Install and Establish DeviceNet Communications

1. Connect the DeviceNet cable to the 5-pin plug (supplied) according to DeviceNet cable wiring specifications.
2. Make sure that the DeviceNet network is terminated properly. (See Section 3.5 below.)
3. The JDM Node Address (MacID) is set to 63 at the factory. Make sure no other device on the network is set to 63, or change the JDM address to one that is not currently used (see Section 2.1).
4. Use the autobaud feature of the JDM.
5. Make sure that there is power on the DeviceNet network and that it is plugged into a Master device.
6. Plug the DeviceNet cable into the JDM.
7. The JDM will undergo its initialization sequence, flashing both LEDs. After approximately 4 seconds, the Module Status LED (labeled "MS") will go on solid green and network LED will flash green.
8. The green Network Status LED (labeled "NS") will go on solid once the Master recognizes the unit on the link and allocates the connection.
9. The JDM is now operating on the network.

2.1 How to Change the Node Address

1. The address is set using the 6-position DIP switch block. They define the address as follows:

Table 2-1 Address Selection

Node Address	Switch Positions					
	1	2	3	4	5	6
	Switch Position Values					
	32	16	8	4	2	1
0	OFF	OFF	OFF	OFF	OFF	OFF
1	OFF	OFF	OFF	OFF	OFF	**ON**
2	OFF	OFF	OFF	OFF	**ON**	OFF
3	OFF	OFF	OFF	OFF	**ON**	**ON**
4	OFF	OFF	OFF	**ON**	OFF	OFF
5	OFF	OFF	OFF	**ON**	OFF	**ON**
…						
62	**ON**	**ON**	**ON**	**ON**	**ON**	OFF
63	**ON**	**ON**	**ON**	**ON**	**ON**	**ON**

(A switch in the OFF position = a value of 0 and in the ON position = a 1.)

2. Switch setting changes do NOT take effect until the device is reset with either a device RESET command (to the class 1 Identity object) or a power cycle.

2.2 How to Change the DeviceNet Baud Rate

1. The baud rate defaults to autobaud. You can change the baud rate in software to a fixed baud rate using your configuration tool or an explicit message to Set Class 3 (DeviceNet Class), Instance 1, Attribute 2 to 1 (125k), 2 (250k), or 3 (500k), from the Master.

2. If you change the baud rate, the new baud rate will not become effective until the unit is power cycled or a Reset command is issued to the JDM from the Master.

2.3 How to Install the Modbus Device Network

1. The communication between the Modbus device(s) and the 1782-JDM is an RS-232 3-wire full-duplex link or an RS-485 network, using a 2-wire half-duplex differential signal between the devices.
2. Connect an appropriate cable to your Modbus device. See your Modbus device users manual for details.
3. Connect the other end of the cable to the JDM using the 3-point terminal plug provided. See Table 2.2 below.
4. Turn on power to the Modbus device.

Table 2-2 JDM Serial Port Connection

Pin #	RS232 Signal	RS485 Signal	Designator
1	Transmit	Signal +	SIG+
2	Receive	Signal -	SIG-
3	Ground	Ground	GND

2.4 How to Read Modbus Device Input Data

1. Set up the poll input data field size in your Master's scan table to be equal to or greater than the number of bytes required for the largest Modbus message received from your device(s). (default size is 48 bytes).

2. Set up a Poll Connection (Allocate Connection Instance 2) to the 1782-JDM from the Master.

3. Configure the serial port to read input data by setting the appropriate values in the Parameter Data, described in Section 3.6.

4. Perform a poll function to the JDM using one of the Modbus read command strings. This will contain the "record number" in the 1st byte (which must be different than the last sent message), followed by the command string as shown in the Modbus RTU specification, WITHOUT the leading colon, the checksum, or the carriage return/linefeed. The JDM will translate this command to the proper Modbus format, compute the checksum, add the colon, carriage return/linefeed (ascii mode), and send the message out the serial port. The JDM will then wait for a reply from the addressed device.

5. The device's response will be received by the JDM, which will check the checksum, and if ok will strip the leading colon, the checksum, and the carriage return/linefeed from the message(in ascii mode), and produce a poll response.

6. The response will include two extra bytes of data. The first byte of the response will be a "record counter" which is a counter generated by the JDM to mark the message with a sequential count value. Each time a new message is received at the JDM from the Modbus network, it will increment the counter.

7. The second byte of the record will be a status byte. This is the status of the Modbus transaction. It will be non-zero if an error occurred, or zero if OK. See Table 2-3 for specific values.

8. The response data bytes will be returned in the mapped poll response data field. The data will be in binary format (ASCII '99' = 99 etc) and will represent the complete Modbus message, less checksum / carriage return/linefeed and the leading ":" (colon) (for ASCII mode).

A typical response is as follows:

- Record count or sequence number (1 byte)
- Status / error data (1 byte)
- Device's Modbus address (1 byte)
- Modbus command number (1 byte)
- Starting Modbus register address (2 bytes)
- Number of data bytes (1 byte)
- 1st Register data (2 byes)
- 2nd Register data (2 byes)
- 3rd Register data (2 byes)

2.5 How to Write Modbus Device Output Data

1. Configure the port to send output data by setting the size of the poll output buffer at the Master to reflect the number of output bytes that will be sent to the Modbus device (default is 48 bytes).

2. Perform a poll function that has the first byte of the field as the "record number", which the host application must increment each time a new record is to sent to the Modbus device. The bytes following this will be the Modbus output command string in binary format, to be sent to the Modbus device, less the leading colon, checksum, and carriage return/linefeed.

3. The JDM will check the record number, and if different from the last received record number, will compute the checksum, add the leading colon and convert the command string to ascii (in ascii mode), and add the carriage return/linefeed. This message is then sent out the serial port to the addressed Modbus device.

4. The JDM will then wait for a reply from the addressed device.

5. When a response is received from the addressed device, the JDM will check the checksum, and if OK, will strip the leading colon and convert the message to binary (in ascii mode), strip the checksum and carriage return/linefeed.

6. A new record number is generated and placed in the 1st byte of the poll response. The 2nd byte is the receiver error byte, with the stripped binary reply following. If no error occurs, the error byte will be zero. Otherwise the status byte (2nd byte in the poll response) will have one of the error values shown in Table 2-3.

The data sent to the JDM will **typically** contain the following info:

- Record sequence number (1 byte)
- Device's Modbus address (1 byte)
- Modbus command number (1 byte)
- Beginning Register number (2 byes)
- Number of registers (2 bytes)
- Output data (2 bytes per datum value)

Table 2-3 Poll Response Status Byte Codes

Error Number	Definition
$E1_{hex}$	Bad Checksum
$E2_{hex}$	Response Address Mismatch
$E3_{hex}$	Response Function Code Mismatch
$E4_{hex}$	Truncated Message received from device
$E5_{hex}$	No Data received from device
$E6_{hex}$	Not Enough Data Received
$E7_{hex}$	Unused

$E8_{hex}$	Carriage Return missing (ascii mode)
$E9_{hex}$	Linefeed Missing (ascii mode)

3 Hardware Installation and Configuration

3.1 Overview

The ASCII contains two LEDs to indicate the status of the device and the status of the network. The device can be connected to the main DeviceNet trunk line or to a drop line via screw terminations on the open, pluggable 5-pin DeviceNet connector supplied with your unit. The serial link, RS232 or RS485, is connected via an open, pluggable 3-pin connector.

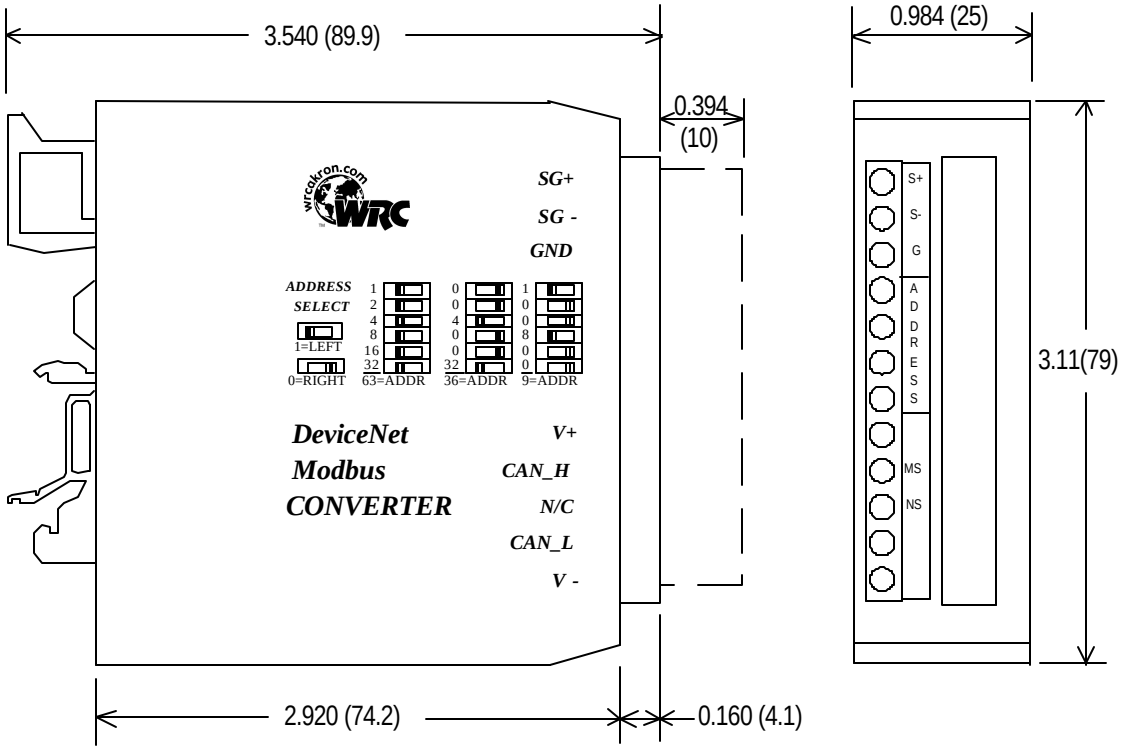

Figure 3-1 1782-JDM Outline

3.2 LED Operation

A ASCII Multiplexer has two LEDs that provide visual status information to the user about the product and the DeviceNet network. See Table 3-1 and Table 3-2.

Table 3-1 Module Status LED (labeled MS)

LED State	Module Status	Meaning
OFF	No Power	There is no power through DeviceNet.
Green	Device Operational	ASCII is operating normally.
Flashing Green	Device in Standby	If in autobaud, ASCII is waiting for a sync signal. (If fixed baud mode, ASCII needs commissioning. Future.)
Flashing Red	Minor Fault	Recoverable fault.
Red	Unrecoverable Fault	ASCII may need replaced.
Flashing Red/Green	Device Self-Testing	ASCII is in self-test mode.

Table 3-2 Network Status LED (labeled NS)

LED State	Module Status	Meaning
OFF	No Power / Not on-line	JDM has no power or has not completed the Dup_MAC_ID test.
Flashing Green	On-line, not connected	JDM is on-line but is not allocated to a Master.
Green	On-line	JDM is operating normally.
Flashing Red	Connection time-out	One or more JDM connections are timed out.
Red	Critical link failure	JDM has detected an error which makes it incapable of communicating on the link. (Bus off or Duplicate MAC ID).

3.3 RS232/RS485 Connector

Your Modbus device(s) are connected to the JDM via 3wire communications cable. See your Modbus device User Manual for details on the specific connection.

Table 3-3 Serial Port Connections

Pin #	RS232 Signal	RS485 Signal	Designator
1	Transmit	Signal +	SIG+
2	Receive	Signal -	SIG-
3	Ground	Ground	GND

3.4 Power Requirements

3.4.1 Device power

The JDM is powered directly from the DeviceNet connection 11-25 Vdc power supply. The JDM consumes 90 mA of current at 24 Vdc, or ~2 Watts, typical.

3.5 Network Configuration

DeviceNet specifications provide for a maximum network distances for the main trunk line and drop lines, depending upon the baud rate used on the network. They are:

Table 3-4 Network Maximum Lengths

Baud Rate	Trunk Line Length		Drop Length			
	Maximum Distance		Maximum		Cumulative	
	Meters	Feet	Meters	Feet	Meters	Feet
125k baud	5OO m	164O ft	6 m	2O ft	156 m	512 ft.
25Ok baud	25O m	82O ft	6 m	2O ft	78 m	256 ft.
5OOk baud	1OO m	328 ft	6 m	2O ft	39 m	128 ft.

3.5.1 Network Termination

A DeviceNet system **must be terminated at each end of the trunk line**. The host controller and the **last** JDM or other DeviceNet device on the network must always be terminated to eliminate reflections, even if only two nodes are present. The DeviceNet specifications for the terminating resistor are:

- 121 ohm
- 1% metal film
- 1/4 Watt

An appropriate terminating resistor kit, WRC part number RM121DN, is included with your JDM.

Important: Per the DeviceNet spec -- do not terminate devices on drop lines.

3.5.2 DeviceNet Connection Wiring

The supplied DeviceNet connection plug accepts cable sizes from 12 AWG - 24 AWG. The maximum wire size (12 AWG) has an area of 653O circular mils and the smallest (24 AWG) has an area of 3265 circular mils.

Where not prohibited by local government or wiring regulations or company policy, multiple wires can be inserted each connection point on the plug as long as the total wire area does not exceed that of a 12 AWG wire. Use the chart below as a guide.

Phoenix Contact recommends using the same size wires be used when connecting more than one wire in a screw termination.

UL may require the use of crimped ferrules to connect multiple wires together.

Table 3-5 DeviceNet Wiring Termination

Wire AWG	Wire area (circular mils)	Maximum Wires per Terminal
12	653O	1
14	411O	1
15	3265	2
16	258O	2
18	162O	4 *
2O	1O22	6 *
22	645	9 *
24	4O4	16 *

* WRC does not recommend using more than 2 wires in any wire terminal.

The conductor sizes for DeviceNet cables are:

Table 3-6 DeviceNet Conductor Sizes

Function	Thick Wire	Thin Wire
Power	15 AWG	22 AWG
Signal	18 AWG	24 AWG

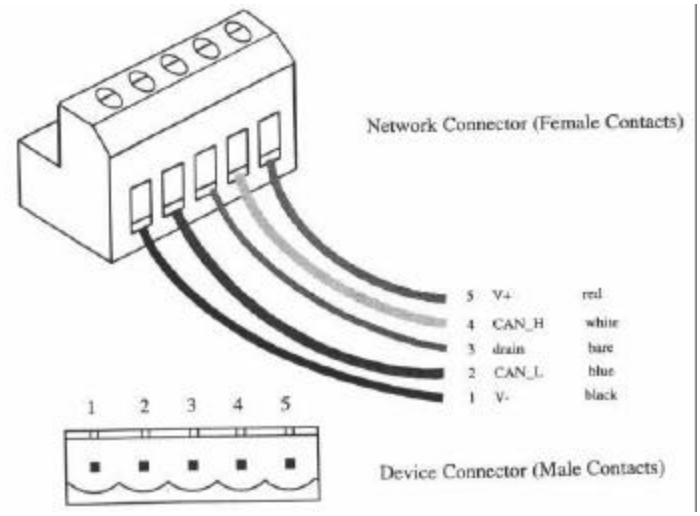

Figure 3-2 DeviceNet cable connector

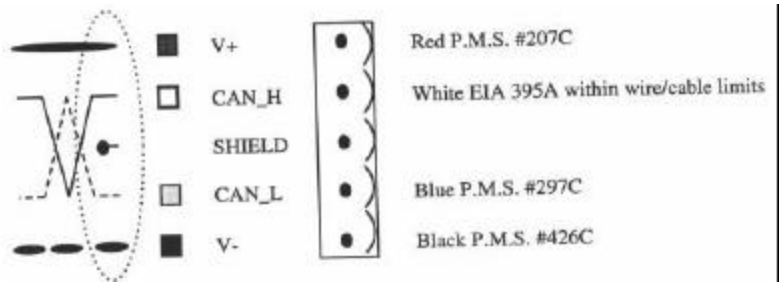

Figure 3-3 DeviceNet cable specifications

3.6 Software Configuration

The ASCII Multiplexer is software-configured for several parameters. Table 3-7 below defines the legal values and the default values for the device address (referred to as the device's MacID), baud rate and ASCII configuration selections available.

Table 3-7 Configuration Parameters

Parameter	Param. Instance	Description	Parameter Choices		Default Setting	Default Value
Modbus Mode	1	Modbus communication protocol	0 = ASCII, 1 = RTU		ASCII	0
Device Rx Data Size	2	Max size of bytes received from the Modbus device	0 – 100		48	48
Device Tx Data Size	3	Max size of bytes transmitted to the Modbus device	0 – 100		48	48
Modbus Baud rate	4	Serial link communication speed	0 = 9600 3 = 1200 4 = 2400	5 = 4800 6 = 19.2k 7 = 38.4k	9600	0
DeviceNet Baud rate	5	DeviceNet communication speed	0 = 125k, 1 = 250k 2 = 500k, 3 = Autobaud		Autobaud	3
Modbus Time-out Time	6	Timeout in 10 ms ticks for a Modbus response	0 = No time out 1 – 255 = 10 ms to 2.55 sec		No time-out	0
Output Fault Action	7	Action to take upon a fault of the DeviceNet communication link	0 = No Action 1 = Transmit String		No Action	0
Output Fault Value / string	8	The string sent out the port if Output Fault Action is 1.	<user-defined string> (up to 100 bytes)		Read Exception Status Command	01, 07
Output Idle Action	9	Action to take upon an Idle condition of the DeviceNet communication link	0 = No Action, 1 = Transmit String		No Action	0
Output Idle Value / string	10	The string sent to out the port if Output Idle Action is 1.	<user-defined string> (up to 100 bytes)		Read Exception Status Command	01, 07
Serial communication framing format	11	Framing parameters for the serial communication link	0 = 7,N, 2 1 = 7, O, 1 2 = 7, E, 1	3 = 8,N, 2 4 = 8, O, 1 5 = 8, E, 1	7N2	0

Definitions of these parameters are as follows:

1. **Modbus Mode**: The JDM can operate in either the ASCII or RTU mode for Modbus communications.

2. **Rx Data Length**: Maximum number of bytes expected from the remote Modbus device. Note that the DeviceNet **produce length** will read this length + 2.

3. **Tx Data Length**: Maximum number of bytes to be sent to the remote Modbus device. Note that the DeviceNet **consume length** will read this length + 1.

4. **Modbus Baud rate**: The communications speed of the RS232 or RS485 link.

5. **DeviceNet Baud rate**: The selection of the baud rate is independent of any other parameter.

6. **Modbus Timeout**: The amount of time the JDM waits for a command response from a Modbus device before it declares an error due to a lack of response from the device. A value of 0 indicates that this feature is not active.

7. **Output Fault Action**: Selection to determine whether each output will hold its last state or transmit the Modbus string identified in the next parameter upon a device fault.

8. **Output Fault Value/String**: The message string the JDM will output after a Fault, if Fault Value is selected above (hold last state is not selected). The default is a command to Modbus address 0x01 with a Modbus command number 0x07, Read Exception Status.

9. **Output Idle Action**: Selection to determine whether each output will hold its last state or transmit the Modbus string defined in the next parameter if an Idle Command is issued by the Master.

10. **Output Idle Value/String**: The message string the JDM will output after an Idle Command, if Idle Value is selected above (hold last state is not selected). The default is a command to Modbus address 0x01 with a Modbus command number 0x07, Read Exception Status.

11. **Serial Communications Framing Format**: Selects which format of communications protocol is used, with the valid selection indicated.

4 DeviceNet I/O Assembly Formats

The following tables define the format of the DeviceNet data sent to and received from the JDM. The exact format of the output and input data that is sent from and received at your DeviceNet master is defined by the Modbus command used. The following tables provide the general format and illustrate the differences between the ASCII and RTU modes. Review the Modbus spec or your Modbus device's user's manual for more details.

4.1 Output Data, Modbus Command

There are two types of output command assembly formats. The output command format depends upon whether or not the command data length is less than or equal to 7 bytes or is 8 or more bytes.

If the command length is 8 bytes or more, then a "fragmented message" is created by the host and is sent to the JDM. This will be the more common format for your Modbus command strings and the format that the JDM expects to receive. See Table 4-1.

Table 4-1 I/O Assembly Object Instance 2 Data Format – Fragmented Command

Byte (Offset value)	Data
0	Record number
1	Address
2	Command
3	Data www – LSB
4	Data www – MSB
5	Data xxx – LSB
6	Data xxx – MSB
…	
N	Last data – LSB
N + 1	Last data – MSB

If the Modbus command string data is 7 bytes or less, then use the command format shown in Table 4-2. This will generate a "non-fragmented DeviceNet message". The 3F (hex) leading byte value indicates to the JDM that this message is be a short string that was not fragmented by the sender.

Table 4-2 I/O Assembly Object Instance 2 Data Format – Short Command w/o Fragmentation

Byte (Offset value)	Data
0	3F (hex)
1	Record number
2	Address
3	Command
4	Data www – LSB
5	Data www – MSB
6	Data xxx – LSB
7	Data xxx – MSB

4.2 Input Data, Modbus Response

The exact format of the input data that is received at your DeviceNet master is defined by the Modbus command used. The following tables provide the general format and illustrate the differences between the ASCII and RTU modes. Review the Modbus spec or your Modbus device's user's manual for more details.

Table 4-3 I/O Assembly Object Instance 1 Data Format – Response

Byte (Offset value)	Data
0	Record number
1	Status
2	Address
3	Function/Command
4	Byte Count
5	Data xxx - LSB
6	Data xxx - MSB
7	Data yyy - LSB
8	Data yyy - MSB
…	
N	Last data - LSB
N + 1	Last data - MSB

For the input assembly to the host, the user does not need be concerned with differentiating between fragmented and non-fragmented messages. This will be done transparently by the JDM and the host processor.

5 General Specifications

Product: 1782-JDM – DeviceNet-to-Modbus Gateway

Description: Communications gateway between a Modbus device over an RS232 or RS485 network and a DeviceNet network. The family members include:

- 1782-JDM-1 – RS232 serial interface
- 1782-JDM-2 – RS485 serial interface
- 1782-JDM-3 – Isolated RS232 serial interface

Device Profile: General Purpose Discrete I/O, Class 7, with objects:

- Identity	(Class 1)
- Message Router	(Class 2)
- DeviceNet	(Class 3)
- Assembly	(Class 4) – 2 instances
- Connection	(Class 5)
- Parameter	(Class F_{hex}) – 9 instances
- Modbus Object	(Class 66_{hex}) – vendor-specific

DeviceNet Conformance: Designed to conform to the ODVA DeviceNet Specification Volume I, Version 2.0 and Volume II, Version 2.0.

Communications: Predefined Master/Slave Connection Set, Group 2 Only Server

DeviceNet I/O Protocols: Poll

DeviceNet Baud Rate: Autobaud (default), 125k, 250, 500k - software selectable

DeviceNet Address selection: Address number 1 to 63, switch selectable (default = 63)
Switches 1 – 6
All switches OFF: address = 0
All switches ON: address = 63

DeviceNet Connection: 5-pin pluggable header (male)
Phoenix Contact MSTBA 2.5/5-G-5.08/AU

DeviceNet Cable: 5-contact plug (female contacts) – color-coded
Phoenix Contact MSTB 2.5/5-ST-5.08/AU
(not included, user supplied)

Modbus Connection: 3-pin pluggable header (male)
Phoenix Contact MSTBA 2.5/3-G-5.08/AU

Modbus Serial Cable: 3-contact plug (female contacts) – color-coded
Phoenix Contact MSTB 2.5/3-ST-5.08/AU (not included, user supplied)

DeviceNet: **Baud rate selection:**

Autobaud operation (default)

Fixed baud (software selectable) – 125k, 250k and 500k baud

Address selection:

Address number 0 to 63, switch selectable (default = 63)

Status Indicators: Module Status: green/red bi-color LED

		Network Status: green/red bi-color LED
	Network Termination: External terminating resistor (optional per user system configuration)	
Serial port:	**Baud rate**: 1200, 2400, 4800, 9600, 19.2k, 39.4k baud	
	software selectable	
	Parity:	Odd, even c
	Data bits: 7 or 8 (software selectable)	
	Status Indicators:	Transmit Active: green LED
		Receive Active: green LED
Voltage Isolation:	Optional 500V isolated RS232 version	
Maximum power:	200 mA @ 11 Vdc / 90 mA @ 25V dc unregulated power supply	
Mounting:	DIN rail mount, EN50022	
Size:	Depth: 3.54" (90 mm) Width: 0.98" (25 mm) Height: 3.11" (79 mm)	
Operating Temp:	0-60 ºC	
Humidity:	0-95% RH, non-condensing	
Agency Approvals:	UL listed (pending), CE (pending)	

6 Accessories and Other WRC Products

The following components can be used with a 1782-JDM-x for replacements or spare parts, or as complementary devices as a part of your DeviceNet system.

Table 6-1 WRC Replacements, Spare Parts and Other Products

Part	WRC Part Number
DIN rail	WRC 50022
Terminating resistor, axial lead	RM121DN
Terminal block connector plug, 18-position	KPELFP18210
Terminal block connector plug, 20-position	KPELFP20210
Discrete I/O block – 4 channels	1782-JDB4
Discrete I/O block – 8 channels	1781-JDB8
Analog Input block – 4 channels, 10-bit	1782-JDA4
Analog I/O block – 8 channels, 12-bit	1782-JDA8
DeviceNet to Serial I/O Gateway	1782-JDC
DeviceNet to Modbus Gateway	1782-JDM
Discrete I/O block – 24 channels	WRC1-JDB24
Discrete I/O block – 48 channels	WRC1-JDB48
Discrete I/O, Analog Input block – 24 DIO, 32 AI	WRC1-JDA/24
Discrete I/O, Analog Input block – 48 DIO, 32 AI	WRC1-JDA/48
Analog I/O block - 32 channels	WRC1-JDAIO
Discrete and Analog I/O block – 24 DIO, 32 AIO	WRC1-JDAIO/24
Discrete and Analog I/O block – 48IO, 32 AIO	WRC1-JDAIO/48
Discrete I/O block – 8 DIs, 8 DOs, 4 AIs	W5-JDM16-x
DeviceNet, CANopen Extender, DIN mount	WRC-CANX-DIN-DN
SDS Extender, DIN mount	WRC-CANX-DIN-SD
DeviceNet, CANopen Extender, DIN mount	WRC-CANX-DIN-C7
DeviceNet, CANopen Extender, NEMA box	WRC-CANX-NEM-AU
DeviceNet, CANopen Extender, NEMA box	WRC-CANX-NEM-DN
SDS Extender, NEMA box	WRC-CANX-NEM-SD
DeviceNet, CANopen Extender, Fiber Optic, NEMA box	WRC-CANR-DF-DN

7 Troubleshooting

This section identifies some of the common problem observed when commissioning or operating a DeviceNet and JDM.

Problem: JDM powers up.
The module LED flashes green.
The network LED is OFF.
JDM does not communicate over the network.
Possible Solution:
The JDM is in Autobaud mode, and is waiting for a few messages to cross the network so it may determine the baudrate setting. This should happen if any other devices send their Dup Mac messages, or the scanner sends any messages over the network. If the JDM is the only device on the network, it may be advisable to set the baudrate to a fixed speed. Check Parameter 5 in Table 3-7

Problem: JDM powers up.
The network status LED flashes red.
JDM does not communicate over the network.
Possible Solution:
JDM has detected a duplicate MacID (DeviceNet address). Change the JDM's MacID to an unused address and cycle power.

Problem: Module Status LED is solid Green
Network Status LED is flashing Green
Device will not communicate on the network.
Possible Solution:
Network does not have a terminating resistor. Add a 121 ohm resistor across the CAN_H and CAN_L signals at the first and last nodes.

Problem: Module Status LED is solid Green
Network Status LED is solid Green
Device will not perform serial I/O – does not return a poll response and ignores future commands.
Possible Solution:
JDM received an unintelligible response from the Modbus device and the time-out is set to 0. Set the time-out value to a non-zero number greater than the longest message time expected from the Modbus device.

Problem: JDM does not receive a response from the Modbus slave.
Possible Solutions:

1. The ASCII-RTU mode selection is not correct. Check Parameter 1 in Table 3-7.
2. The serial link baud rate does not match the Modbus device baud rate. Check Parameter 4 in Table 3-7.
3. The communication Framing parameters are not correct. Check Parameter 11 in Table 3-7.
4. The Modbus address is not correct in the I/O command.
5. The Modbus device may not support the Modbus specific commands being issued.